

SFAR-1M-2DI2DO

User Manual

Expansion Module - 2 Digital Inputs, 2 Digital Outputs





Global Control 5 Sp. z o.o. Warsaw, Poland www.gc5.pl

Version 3.0 Page 1 / 13

Table of contents

| 1. | Safety rules | 4 |
|----|--|---|
| 2. | Module features | 4 |
| | 2.1. Purpose and description of the module | 4 |
| | 2.2. Technical specifications | 5 |
| | 2.3. Dimensions of the product | |
| 3. | COnfigurating of the communication | 6 |
| | 3.1. Grounding and shielding | 6 |
| | 3.2. Network termination | 7 |
| | 3.3. Types of Modbus Registers | 7 |
| | 3.4. Communication settings | 7 |
| | 3.4.1. Default settings | 7 |
| | 3.4.2. Configuration registers | |
| | 3.4.3. Watchdog information | |
| | Indicators | |
| 5. | Module Connection | 9 |
| | 5.1. Block diagram | 9 |
| | 5.2. Connection of outputs1 | 0 |
| | 5.3. Connection of inputs | 0 |
| 6. | Modules Registers | 0 |
| | 6.1. Registered access | 0 |
| | 6.2. Bit access | |
| 7. | Configuration software1 | 3 |

Thank you for choosing our product.

This manual will help you with proper handling and operating of the device.

The information included in this manual have been prepared with utmost care by our professionals and serve as a description of the product without incurring any liability for the purposes of commercial law.

This information does not discharge you from the liability of your own judgement and verification.

We reserve the right to change product specifications without notice.

Please read the instructions carefully and follow the recommendations concluded therein.

WARNING!

Failure to follow instructions can result in equipment damage or impede the use of the hardware or software.

1. Safety rules

- 1. Refer to this manual before the first use
- 2. Make sure that all cables are connected properly before the first use
- 3. Please ensure proper working conditions, according to the device specifications (e.g., supply voltage, temperature, maximum power consumption)
- 4. Turn the power supply off before making any modifications to wiring connections.

2. Module features

2.1. Purpose and description of the module

2DI2DO Module is an innovative device that provides a simple and cost-effective extension of the number of lines of input in popular PLCs.

The module has 2 Digital Inputs with configurable timer/counter option which allows to connect one encoders. All inputs are isolated from the logic by optocouplers. Each channel can be individually configured in one of several modes.

This module is connected to the RS485 bus with twisted-pair wire. Communication is via Modbus RTU or Modbus ASCII. The use of 32-bit ARM core processor provides fast processing and quick communication. The baud rate is configurable from 2400 to 115200.

The module is designed for mounting on a DIN rail in accordance with DIN EN 5002.

The module is equipped with a set of LEDs to indicate the status of inputs and outputs which is useful for diagnostic purposes and helping to find errors.

Module configuration is done via USB by using a dedicated computer program. You can also change the parameters using the Modbus protocol.

2.2. Technical specifications

| | Voltage | 10-38 V DC; 10-28 V AC | | |
|-----------------|--------------------------------|------------------------|--|--|
| Power Supply | | 1 W @ 24 V DC | | |
| | Power consumption ¹ | 2 VA @ 24 V AC | | |
| | No of inputs | 2 | | |
| | Voltage range | 0 – 36 V | | |
| | Low State "0" | 0 – 3 V | | |
| Digital Inputs | High State "1" | 6 – 36 V | | |
| | Input impedance | 4 kΩ | | |
| | Isolation | 1500 Vrms | | |
| | Input Type | PNP or NPN | | |
| | No | 2 | | |
| Counters | Resolution | 32 bits | | |
| Counters | Frequency | 1 kHz (max) | | |
| | Impulse Width | 500 μs (min) | | |
| | No of outputs | 2 | | |
| | Max Voltage | 55 V | | |
| Digital Outputs | Max current | 250 mA | | |
| | Output Type | PNP | | |
| | Isolation | 1500 Vrms | | |
| Temperature | Work | -20°C - +65°C | | |
| remperature | Storage | -40°C - +85°C | | |
| | Power Supply | 3 pin | | |
| Connectors | Communication | 3 pin | | |
| Connectors | Inputs | 2 x 3 pin | | |
| | Configuration | Mini USB | | |
| | Height | 90 mm | | |
| Size | Length | 56,4 mm | | |
| | Width | 17,5 mm | | |
| Interface | RS485 | Up to 128 devices | | |

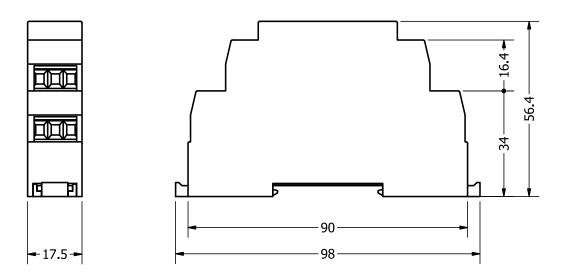
Table 1 - Technical specifications

Version 3.0 www.gc5.pl Page 5 / 13

¹ Power consumption with active Modbus transmission and high state on all inputs

2.3. Dimensions of the product

The appearance and dimensions of the module are shown below. The module is mounted directly to the rail in the DIN industry standard. Power connectors, communication and IOs are at the bottom and top of the module. USB connector configuration and indicators located on the front of the module.



Picture 1 - Dimensions of the product

3. Configurating of the communication

3.1. Grounding and shielding

In most cases, IO modules will be installed in an enclosure along with other devices which generate electromagnetic radiation. Examples of these devices are relays and contactors, transformers, motor controllers etc. This electromagnetic radiation can induce electrical noise into both power and signal lines, as well as direct radiation into the module causing negative effects on the system. Appropriate grounding, shielding and other protective steps should be taken at the installation stage to prevent these effects. These protective steps include control cabinet grounding, module grounding, cable shield grounding, protective elements for electromagnetic switching devices, correct wiring as well as consideration of cable types and their cross sections.

3.2. Network termination

Transmission line effects often represent the problem of data communication networks. These problems include reflections and signal attenuation.

To eliminate the presence of reflections at the end of the cable, the cable must be terminated at both ends with a resistor across the line equal to its characteristic impedance. Both ends must be terminated since the direction of propagation is bi-directional. In the case of RS485 twisted pair cable this termination is typically $120~\Omega$.

3.3. Types of Modbus Registers

There are 4 types of variables available in the module

| Туре | Beginning address | Variable | Access | Modbus Command |
|------|----------------------|------------------|----------------------------|-------------------|
| 1 | 00001 | Digital Outputs | Bit Read & Write | 1, 5, 15 |
| 2 | 10001 | Digital Inputs | Bit Read | 2 |
| 3 | 30001 | Input Registers | Registered Read | 3 |
| 4 | 40001 | Output Registers | Registered Read & Write | 4, 6, 16 |

Table 2 - Types of variables

3.4. Communication settings

The data stored in the module's memory is given in the 16-bit registers. the access to registers happens via Modbus RTU or Modbus ASCII.

3.4.1. Default settings

| Parameter name | Value |
|------------------|-------|
| Address | 1 |
| Baud rate | 19200 |
| Parity | No |
| Data bits | 8 |
| Stop bits | 1 |
| Reply Delay [ms] | 0 |
| Modbus Type | RTU |

Table 3 - Default settings

3.4.2. Configuration registers

| Modbus | Dec | Hex | Name | Values | |
|--------|--------|------|----------------|---|--|
| А | ddress | | Name | values | |
| 40003 | 2 | 0x02 | Baud rate | 0 - 2400 1 - 4800 2 - 9600 3 - 19200 4 - 38400 5 - 57600 6 - 115200 other - value * 10 | |
| 40005 | 4 | 0x04 | Parity | 0 - none 1 - odd 2 - even 3 - always 1 4 - always 0 | |
| 40004 | 3 | 0x03 | Stop Bits LSB | 1 – one stop bit 2 – two stop bits | |
| 40004 | 3 | 0x03 | Data Bits MSB | 7 – 7 data bits 8 – 8 data bits | |
| 40006 | 5 | 0x05 | Response delay | Time in ms | |
| 40007 | 6 | 0x06 | Modbus Mode | 0 - RTU 1 - ASCII | |

Table 4 - Configuration registers

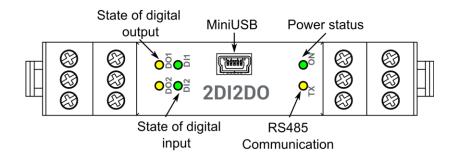
3.4.3. Watchdog information

This 16-bits register specifies the time in milliseconds to watchdog reset. If module does not receive any valid message within that time, all Digital and Analog Outputs will be set to the default state.

This feature is useful if there is an interruption in data transmission and for security reasons. Output states must be set to the appropriate state in order to reassure the safety of persons or property.

The default value is 0 milliseconds which means the watchdog function is disabled.

4. Indicators



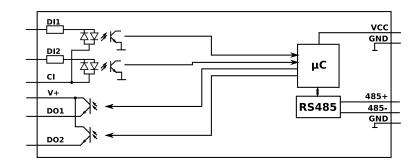
Picture 2 - Indicators

| Indicator | Description |
|-----------|---|
| ON | LED indicates that the module is correctly powered. |
| TX | The LED lights up when the unit received the correct packet and sends the answer. |
| DI1, DI2 | LED indicates that on the input is high state. |
| DO1, DO2 | LED indicates that the output is on. |

Table 5 - Description of indicators

5. Module Connection

5.1. Block diagram

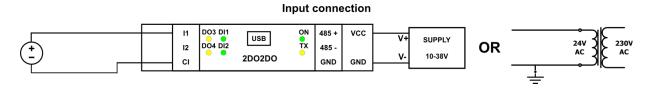


Picture 3 - Block diagram

5.2. Connection of outputs

Picture 4 – Connection of outputs

5.3. Connection of inputs



Picture 5 - Connection of inputs

6. Modules Registers

6.1. Registered access

| Modbus | Dec | Hex | Register Name | Access | Description | |
|--------|-----|------|-----------------------|--------------|---|--|
| 30001 | 0 | 0x00 | Version/Type | Read | Version and Type of the device | |
| 30002 | 1 | 0x01 | Address | Read | Module Address | |
| 40003 | 2 | 0x02 | Baud rate | Read & Write | RS485 baud rate | |
| 40004 | 3 | 0x03 | Stop Bits & Data Bits | Read & Write | No of Stop bits & Data Bits (see 3.4.2.) | |
| 40005 | 4 | 0x04 | Parity | Read & Write | Parity bit | |
| 40006 | 5 | 0x05 | Response Delay | Read & Write | Response delay in ms | |
| 40007 | 6 | 0x06 | Modbus Mode | Read & Write | Modbus Mode (ASCII or RTU) | |
| 40009 | 8 | 0x08 | Watchdog | Read & Write | Watchdog | |
| 40013 | 12 | 0x0C | Default Output State | Read & Write | Default output state (after power on or watchdog reset) | |
| 40033 | 32 | 0x20 | Received packets MSB | Read & Write | No of received pookets | |
| 40034 | 33 | 0x21 | Received packets LSB | Read & Write | No of received packets | |
| 40035 | 34 | 0x22 | Incorrect packets MSB | Read & Write | No of received populate with error | |
| 40036 | 35 | 0x23 | Incorrect packets LSB | Read & Write | No of received packets with error | |
| 40037 | 36 | 0x24 | Sent packets MSB | Read & Write | No of sent packets | |

| Modbus | Dec | Hex | Register Name | Access | Description |
|-----------------------------------|-----|------------------|------------------|--------------|--|
| 40038 | 37 | 0x25 | Sent packets LSB | Read & Write | |
| 30051 | 50 | 0x32 | Inputs | Read | Inputs state |
| 40052 | 51 | 0x33 | Outputs | Read & Write | Output state |
| 40053 | 52 | 0x34 | Counter 1 MSB | Read & Write | 32-bit counter 1 |
| 40054 | 53 | 0x35 | Counter 1 LSB | Read & Write | Sz-bit counter 1 |
| 40055 | 54 | 0x36 | Counter 2 MSB | Read & Write | 32-bit counter 2 |
| 40056 | 55 | 0x37 | Counter 2 LSB | Read & Write | Sz-bit counter z |
| 40061 | 60 | 0x3C | CCounter 1 MSB | Read & Write | 32-bit value of captured counter 1 |
| 40062 | 61 | 0x3D | CCounter 1 LSB | Read & Write | 52-bit value of captured counter 1 |
| 40063 | 62 | 0x3E | CCounter 2 MSB | Read & Write | 32-bit value of captured counter 2 |
| 40064 | 63 | 0x3F | CCounter 2 LSB | Read & Write | 52-bit value of captured counter 2 |
| 40069 | 68 | 0x44 | Counter Config 1 | Read & Write | Counter Configuration |
| 40070 | 69 | 0x45 | Counter Config 2 | Read & Write | +1 - time measurement (if 0 counting impulses) +2 - autocatch counter every 1 sec +4 - catch value when input low +8 - reset counter after catch +16 - reset counter if input low +32 - encoder |
| 40073 | 72 | 0x48 | Catch | Read & Write | Catch counter |
| 40074 73 0x49 Status Read & Write | | Captured counter | | | |

Table 6 - Registered access

6.2. Bit access

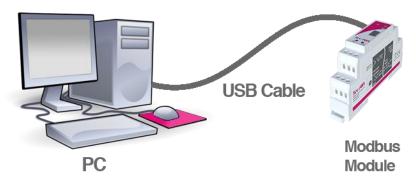
| Modbus Address | Dec Address | Hex Address | Register name | Access | Description |
|-------------------|----------------|----------------|---------------------------|--------------|-----------------------------|
| 193 | 192 | 0x0C0 | Default state of output | Read & Write | Default state of output 1 |
| 194 | 193 | 0x0C1 | Default state of output 2 | Read & Write | Default state of output 2 |
| 10801 | 800 | 0x320 | Input 1 | Read | Input 1 state |
| 10802 | 801 | 0x321 | Input 2 | Read | Input 2 state |
| 817 | 816 | 0x330 | Output 1 | Read & Write | Output 1 state |
| 818 | 817 | 0x331 | Output 2 | Read & Write | Output 2 state |
| 1153 | 1152 | 0x480 | Capture 1 | Read & Write | Capture counter 1 |
| 1154 | 1153 | 0x481 | Capture 2 | Read & Write | Capture counter 2 |
| 1169 | 1168 | 0x490 | Captured 1 | Read & Write | Captured value of counter 1 |
| 1170 | 1169 | 0x491 | Captured 2 | Read & Write | Captured value of counter 2 |

Table 7 - Bit access

7. Configuration software

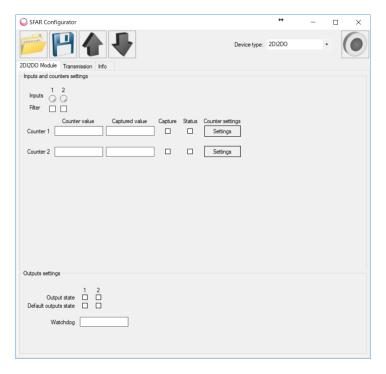
Modbus Configurator is the type of software which is designed to set the communication module registers over Modbus network as well as to read and write the current value of other registers of the module. It's a convenient way to test the system as well as to observe real-time changes in the registers.

Communication with the module happens via the USB cable. The module does not require any drivers.



Picture 6 - Configuration process

Configurator is an universal software, whereby it is possible to configure all available modules.



Picture 7 - Configurator